

AVERAGE-CASE “MESSY” BROADCASTING

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Received 27 August 2004

Revised 26 November 2006

Current studies of “messy” broadcasting have so far concentrated on finding worst-case times. However, such worst-case scenarios are extremely unlikely to occur in general. Hence, determining average-case times or tight upper bounds for completing “messy” broadcasting in various network topologies is both necessary and meaningful in practice. In this paper, we focus on seeking the average-case “messy” broadcast times of stars, paths, cycles, and d -ary trees, and finding good upper bounds for hypercubes. Finally, we derive a recursive formula to express the average-case time for a specific “messy” broadcast model on a complete graph using a classical occupancy problem in probability theory, and provide a nice simulation result which indicates that this model behaves like classical broadcasting.

Keywords: “Messy” broadcasting; network topology; hypercube; d -ary tree; average-case analysis.

1. Introduction

Broadcasting is an information dissemination problem in which we model a computer network using a graph $G = (V, E)$. The main motivation of broadcasting research is to provide a theoretical structure for general interconnection networks for multiprocessor computers. One vertex, the *originator*, has a message which it must distribute to all other vertices. A

vertex v may communicate with any other vertex adjacent to v , and communication takes place in discrete time units. There are many variants of the broadcasting problem (classical broadcasting, k -broadcasting, reliable broadcasting, etc.); a survey of these problems is given in [10]. “Messy” broadcasting is the variant which is the subject of this paper.

In the classical broadcast model, it is assumed that every vertex in a network broadcasts optimally. Such a model therefore requires either

- a leader who knows the network’s topology and coordinates the actions of all members during the entire broadcasting process, which seems unrealistic in practice; or,
- that each vertex must have a coordinated set of protocols with respect to any originator, the space to store these protocols, and each message must be labeled with the originator and the time at which the message was sent.

“Messy” broadcasting does away with these assumptions, instead assuming that the network’s vertices have no knowledge of the network’s topology, and that when a vertex receives a message it knows neither the originator of the message, nor the time at which the message was sent. The vertices are therefore unable to devise any sophisticated broadcast scheme, but the network can be built more cheaply and easily. This variant of broadcasting was introduced by Ahlswede, Haroutunian, and Khachatrian in [1]. The worst case problems on various network topologies such as paths, cycles, hypercubes, and d -ary trees were studied by Harytyunyan and Liestman in [9]. Hart and Harytyunyan derived the “messy” broadcast times for complete bipartite graphs and improved the lower bound for “messy” broadcast times on hypercubes of arbitrary dimension in [8]. In [2], Comellas, Harutyunyan, and Liestman determined the exact values and bounds for the broadcast times on multi-dimensional directed tori.

A survey of existing methods of communication in usual networks was given by P. Fraignaud and E. Lazard [6] which focused on the study of complete networks, the ring, the torus, the grid, the hypercube, the cube connected cycle, undirected de Bruijn graphs, the star graph, the shuffle-exchange graph, and the butterfly graph with the constant model and the linear model. In [11] Hromkovic, Klasing, Monien, and Peine summarized the main techniques and results relating to broadcasting and gossiping problems using a one-way communication mode.

At each time unit every informed vertex broadcasts randomly to a neighbor which it believes is uninformed. There are three models of “messy” broadcasting, and each makes different assumptions about how a vertex v comes to believe that its neighbor u is informed:

- **Model M_1 :** v believes that u is informed iff u is informed.
- **Model M_2 :** v believes that u is informed iff either v has informed u or u has informed v .
- **Model M_3 :** v believes that u is informed iff v has informed u .

Note that we assume that each informed vertex may broadcast to only one neighbor during each time unit. Assuming that vertices may broadcast to $k \geq 2$ neighbors in a single

time unit would yield “messy” k -broadcasting, a problem which, to our knowledge, has yet to be investigated. Since in our study the number of informed vertices may at most double during a single time unit, no “messy” broadcast scheme can be completed in fewer than $\lceil \log_2 n \rceil$ time units, where n is the number of nodes in the network in question. We consider broadcasting to be completed when each node in the network has received the message.

We follow the notation of [1] and [9], with some additions to accommodate our average-case analysis.

Let $u \in G$ be the originator of a “messy” broadcast. We say that $\sigma(u)$ is a *strategy* or *scheme* for model M_i for $i = 1, 2, 3$ iff all calls in $\sigma(u)$ are legitimate under model M_i , and $\sigma(u)$ informs all vertices in G . For $i = 1, 2, 3$, let $\Omega_i(u) = \{\sigma(u) \mid \sigma(u) \text{ is legitimate under model } M_i\}$ be the set of all broadcast strategies from the originator u under model M_i .

We define $t_i(u)$ to be the maximum time of any scheme in $\Omega_i(u)$, and we define $t_i(G) = \max\{t_i(u) \mid u \in G\}$. We also define $T_{i,u,G}^{\sigma(u)}$ to be the time taken to inform all vertices in G according to the “messy” broadcast scheme $\sigma(u) \in \Omega_i(u)$. We can now define the *average “messy” broadcast time of u in G under M_i* to be

$$E[T_{i,u,G}] = \frac{\sum_{\sigma(u) \in \Omega_i(u)} T_{i,u,G}^{\sigma(u)}}{|\Omega_i(u)|}.$$

Furthermore, we define the *average “messy” broadcast time of G under M_i* to be

$$E[T_{i,G}] = \sum_{k=1}^{|V(G)|} E[T_{i,u_k,G}] Pr\{u_k\}, \quad (1.1)$$

where $Pr\{u_k\}$ is the probability of u_k being the originator of a “messy” broadcast in G . Of course, these probabilities must be chosen such that $\sum_{k=1}^{|G|} Pr\{u_k\} = 1$. Throughout this paper, we will assume that $Pr\{u\} = \frac{1}{|G|}$ for all $u \in G$; however, allowing the probabilities to be chosen in other ways gives us the opportunity generalize the model by choosing a high probability for an originator that can distribute a message quickly over a network topology, thereby speeding up the average broadcast time.

In [9], Harutyunyan and Liestman investigated the worst-case times to complete “messy” broadcasting under M_1 , M_2 and M_3 in hypercubes, complete d -ary trees, and some simple graphs. These times are highly improbable for almost all popular topologies, and the probability for these worst-case times to occur is almost zero when the number of vertices in a network is large. The objective of this paper is to open a new direction of research in the area of “messy” broadcasting - the study of average case “messy” broadcast times, which certainly play an important role in determining the efficiency of networks. In sections 2 and 4 we focus on finding exact values for the average case “messy” broadcast times on stars, paths, cycles and complete d -ary trees. In section 4 we investigate the hypercube structure and provide tight upper bounds on “messy” broadcast times under models M_2 and M_3 , which are far better than the worst-case times. As an example to illustrate difference between worst-case and average-case times, Theorem 3.1 of [9] states that the worst-case time to finish “messy” broadcasting under model M_3 on a d -dimensional hypercube is $d(d+1)/2$, and we estimate that the probability of randomly-chosen “messy” broadcast scheme taking

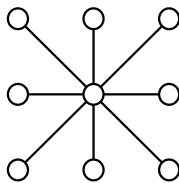


Fig. 1. A star graph on 9 vertices.

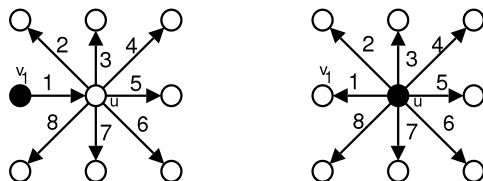


Fig. 2. Messy broadcasting in star graphs under models M_1 and M_2 . We adopt the convention of drawing the originator in black.

this many time units is far less than $1/d^d$, which vanishes very quickly when d is increasing. However, the average-case time we find in Section 3 is significantly better and is bounded by

$$(d + 1) \sum_{j=1}^d \frac{1}{j} = \Theta(d \log d).$$

In addition, we believe that the average “messy” broadcast time for a complete graph is $\lceil \log n \rceil + 2$ (see Section 5), which is much faster than the worst-case time of $n - 1$, where n is the total number of vertices. Our intuition is guided by simulations we performed for several graphs under all three models, which we validate by the proofs presented in this paper.

2. Simple Graphs

In order to demonstrate the techniques and considerations required when examining average-case “messy” broadcasting times, we first look at the analysis of some simple graphs. For these simple graphs, we can calculate average-case “messy” broadcast times in a very straightforward manner.

2.1. Stars

The star S_n has n vertices. One of these vertices (the central vertex) has degree $n - 1$, and the others have degree 1. S_9 , the star on 9 vertices, is shown in Fig. 1. Stars are particularly simple to analyze, since the number of possible “messy” broadcast schemes is very small.

Theorem 2.1. $E[T_{1,S_n}] = E[T_{2,S_n}] = n - 1$, and $E[T_{3,S_n}] = n - 1 + \frac{n-2}{n}$.

Proof. Let u denote the central vertex of S_n , and let the other vertices of S_n be enumerated v_1, v_2, \dots, v_{n-1} .

For models M_1 and M_2 , all legitimate broadcast schemes obviously complete in exactly $n - 1$ time units, as can be confirmed by examining Fig. 2. Hence, $E[T_{1,S_n}] = E[T_{2,S_n}] = n - 1$.

The analysis is slightly more complicated for model M_3 . If the originator is u , then broadcasting must complete in $n - 1$ time units, since u must call its $n - 1$ neighbors at times $1, 2, \dots, n - 1$. If the originator is v_i for some i , then we must consider two cases:

Case 1: Once u is informed, it broadcasts to vertices v_j ($j \neq i$) at times $2, 3, \dots, n - 1$, and broadcasting therefore completes in $n - 1$ time units since all nodes are informed.

Case 2: Once u is informed, it broadcasts to v_i at time j , for some j in the range $2 \leq j \leq n - 1$. Broadcasting therefore completes in n time units.

Given that v_i is the originator, the probability that Case 1 occurs is the probability that u does not inform v_i at time $2, 3, \dots, n - 1$. Given that u has not informed v_i at time $2, 3, \dots, t - 1$, the probability of this occurring at time t is $\frac{n-t}{n-t+1}$. Thus, the probability that Case 1 occurs is given by

$$\frac{n-2}{n-1} \times \frac{n-3}{n-2} \times \frac{n-4}{n-3} \times \dots \times \frac{2}{3} \times \frac{1}{2} = \frac{1}{n-1}.$$

Hence,

$$\begin{aligned} E[T_{3,v_i,S_n}] &= Pr\{\text{Case 1}\} \times (n - 1) + Pr\{\text{Case 2}\} \times n \\ &= n - \frac{1}{n-1}. \end{aligned}$$

For the star S_n , we thus have, by Eq. (1.1), that,

$$\begin{aligned} E[T_{3,S_n}] &= \frac{E[T_{3,u,S_n}] + \sum_{i=1}^{n-1} E[T_{3,v_i,S_n}]}{n} \\ &= n - 1 + \frac{n-2}{n}. \end{aligned}$$

□

Note that this last result could be simplified to $n - \frac{n}{2}$; however, we leave it as $n - 1 + \frac{n-2}{n}$ to show more clearly the base cost of $n - 1$ plus the cost of $\frac{n-2}{n}$ due to poor choices made while broadcasting.

2.2. Paths

A path P_n is a graph on n vertices labeled v_0, v_1, \dots, v_{n-1} where vertex v_k is connected to vertex v_{k+1} for $k = 0, 1, \dots, n - 2$. Paths are only marginally more complex to analyze than the stars.

Theorem 2.2. $E[T_{i,P_1}] = 0$ and $E[T_{i,P_2}] = 1$ for $i = 1, 2, 3$, $E[T_{1,P_3}] = E[T_{2,P_3}] = 2$, and $E[T_{3,P_3}] = \frac{7}{3}$. For $n \geq 4$,

$$E[T_{1,P_n}] = E[T_{2,P_n}] = \begin{cases} \frac{3}{4}n - \frac{1}{n} & \text{if } n \text{ is even} \\ \frac{3}{4}n - \frac{3}{4n} & \text{if } n \text{ is odd, and} \end{cases}$$

$$E[T_{3,P_n}] = \begin{cases} \frac{9}{8}n - \frac{3}{4} - \frac{1}{n} & \text{if } n \text{ is even} \\ \frac{9}{8}n - \frac{3}{4} - \frac{7}{8n} & \text{if } n \text{ is odd.} \end{cases}$$

Proof. The results for $n < 4$ are easy to verify. To prove $E[T_{1,P_3}] = \frac{7}{3}$ we must consider two cases. The first, when v_1 is the originator, is the simplest. At times $k = 1, 2$, v_1 sends the message to v_0 and v_2 with broadcasting completing in 2 time units. This case occurs with probability $\frac{1}{3}$ as each vertex is equally likely to begin broadcasting. The second case, when v_0 or v_2 originates can proceed in two possible ways depending on whether or not v_1 sends the message back to the originator before passing it to the last vertex. If v_1 sends back to the originator then broadcasting completes in 3 time units. Otherwise broadcasting completes in 2 time units. Each of these cases occur with equal probability making the average time to complete 2.5 time units. Combining these times yields

$$E[T_{1,P_3}] = 2 \times \frac{1}{3} + 2.5 \times \frac{2}{3} = \frac{7}{3}.$$

We now consider the general case. In P_n , if a vertex v_k is informed then the only way for an adjacent vertex to be informed is if it was the vertex that informed v_k , or v_k was the vertex that informed it. Thus, $\Omega_1(u) = \Omega_2(u)$ for all $u \in P_n$ for all n ; that is, models M_1 and M_2 are equivalent for paths. We will consider these models first.

Consider the case in which v_0 is the originator. Broadcasting must then complete in $n - 1$ time units; similarly for v_{n-1} . If v_1 is the originator, then broadcasting may complete in either $n - 1$ or $n - 2$ time units, depending on whether v_1 broadcasts to v_0 or v_2 at time 1. Hence $E[T_{1,v_1,P_n}] = n - 2 + \frac{1}{2}$. If v_i is the originator for $i \leq \frac{n}{2}$, then broadcasting completes in either $n - i$ or $n - (i + 1)$ time units depending on whether v_i broadcasts to v_{i-1} or v_{i+1} at time 1. Because each case occurs with equal probability, $E[T_{1,v_i,P_n}] = n - (i + 1) + \frac{1}{2}$. The case for $i > \frac{n}{2}$ is symmetric.

If n is even, then

$$\begin{aligned} \sum_{i=0}^{n-1} E[T_{1,v_i,P_n}] &= 2 \sum_{i=0}^{\frac{n}{2}-1} E[T_{1,v_i,P_n}] \\ &= 2((n - 1) + (n - 2 + \frac{1}{2}) + (n - 3 + \frac{1}{2}) + \dots + (n - \frac{n}{2} + \frac{1}{2})) \\ &= \frac{3}{4}n^2 - 1. \end{aligned}$$

Hence, for even n ,

$$E[T_{1,P_n}] = \frac{\sum_{i=0}^{n-1} E[T_{1,v_i,P_n}]}{n} = \frac{\frac{3}{4}n^2 - 1}{n} = \frac{3}{4}n - \frac{1}{n}.$$

The result follows similarly for odd n .

We now turn our attention to model M_3 , first considering vertex v_0 . There are $n - 1$ edges between v_0 and v_{n-1} . Hence, when v_0 is the originator, it needs at least $n - 1$ time units in order to inform all vertices in P_n . Each of the $n - 2$ vertices v_1, v_2, \dots, v_{n-2} may, upon being informed, broadcast either in the direction of v_0 or v_{n-1} ; that is, for $1 \leq i \leq n - 2$, vertex v_i may broadcast first to v_{i-1} , or to v_{i+1} , and either case occurs with probability $\frac{1}{2}$. For each vertex v_i that broadcasts first in the direction of v_{i-1} , 1 time unit is wasted. Hence,

$$E[T_{3,v_0,P_n}] = n - 1 + \frac{n - 2}{2}.$$

It follows by symmetry that $E[T_{3,v_0,P_n}] = E[T_{3,v_{n-1},P_n}]$.

Vertex v_1 has 1 vertex on one side, and $n - 2$ vertices on the other. If v_1 is the originator, and it broadcasts first to v_0 , then it wastes 1 time unit. By an analysis similar to the case in which v_0 is the originator,

$$E[T_{3,v_1,P_n}] = n - 2 + \frac{n - 3}{2} + \frac{1}{2} = E[T_{3,v_{n-2},P_n}].$$

From our analysis of models M_1 we have $E[T_{1,v_i,P_n}] = n - (i + 1) + \frac{1}{2}$. We can modify this expression for M_3 by taking into account that after time 1, the average time needed to forward the message is now 1.5 due to possibly sending the message back where it came from. Thus,

$$E[T_{3,v_i,P_n}] = n - (i + 1) + \frac{n - (i + 2)}{2} + \frac{1}{2}.$$

Hence, for even n ,

$$\begin{aligned} \sum_{i=0}^{n-1} E[T_{3,v_i,P_n}] &= 2((n - 1 + \frac{n-2}{2}) + (n - 2 + \frac{n-3}{2} + \frac{1}{2}) + \dots \\ &\quad + (n - \frac{n}{2} + \frac{n - (\frac{n}{2} + 1)}{2} + \frac{1}{2})). \end{aligned}$$

For odd n , vertex $v_{\frac{n+1}{2}}$ has $\frac{n-1}{2}$ vertices on either side. Hence,

$$E[T_{3,v_{\frac{n+1}{2}},P_n}] = (\frac{n + 1}{2} - 1) + \frac{(\frac{n+1}{2}) - 2}{2} + 1 = \frac{3n - 1}{4},$$

and we have

$$\begin{aligned} \sum_{i=0}^{n-1} E[T_{3,v_i,P_n}] &= 2((n - 1 + \frac{n-2}{2}) + (n - 2 + \frac{n-3}{2} + \frac{1}{2}) + \dots \\ &\quad + (n - \frac{n-1}{2} + \frac{n - (\frac{n-1}{2} + 1)}{2} + \frac{1}{2})) + \frac{3}{4}(n + 1) - 1. \end{aligned}$$

Simple calculations imply that

$$E[T_{3,P_n}] = \begin{cases} \frac{9}{8}n - \frac{3}{4} - \frac{1}{n} & \text{if } n \text{ is even} \\ \frac{9}{8}n - \frac{3}{4} - \frac{7}{8n} & \text{if } n \text{ is odd.} \end{cases}$$

This completes our proof. □

Paths also give us an opportunity to demonstrate very easily that many worst-case “messy” broadcast times are highly improbable. It was proven in [9] that $t_3(P_n) = 2n - 3$, but this worst-case time occurs only when the originator is v_0 , and, for $1 \leq i \leq n - 2$, v_i broadcasts to v_{i-1} before broadcasting to v_{i+1} , or, by symmetry, when the originator is v_{n-1} and, for $1 \leq i \leq n - 2$, v_i broadcasts to v_{i+1} before broadcasting to v_{i-1} .

Corollary 2.1. $Pr\{T_{3,v_0,P_n} = 2n - 3\} = Pr\{T_{3,v_{n-1},P_n} = 2n - 3\} = \frac{1}{2^{n-2}}$.

Proof. Assume, without loss of generality, that v_0 is the originator. Each vertex v_i , $1 \leq i \leq n - 2$, broadcasts to v_{i-1} before broadcasting to v_{i+1} with probability $\frac{1}{2}$, and these are independent events. The worst-case time of $2n - 3$ occurs only when each v_i broadcasts first to v_{i-1} . There are $n - 2$ vertices between v_0 and v_{n-1} that must first send the message

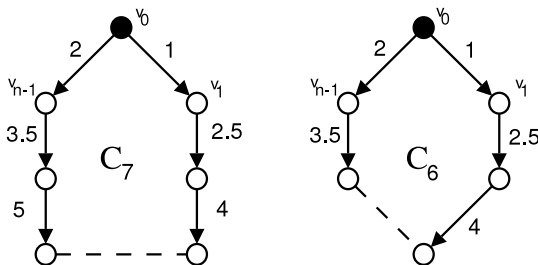


Fig. 3. Average-case messy broadcasting in cycles of odd and even cardinality under model M_3 .

back to v_{i-1} , each doing so with probability $\frac{1}{2}$. Hence, the probability of the worst-case time occurring is $\frac{1}{2^{n-2}}$. □

2.3. Cycles

A cycle C_n on n vertices is a path on n vertices with an additional edge added between v_0 and v_{n-1} . Fig. 3 shows the cycles C_6 and C_7 .

Theorem 2.3. *Let C_n be a cycle on n vertices. Then,*

$$E[T_{1,C_n}] = E[T_{2,C_n}] = \lceil \frac{n}{2} \rceil, \text{ and}$$

$$E[T_{3,C_n}] = \begin{cases} \frac{3n-2}{4} & \text{if } n \text{ is even} \\ \frac{3n-1}{4} & \text{if } n \text{ is odd.} \end{cases}$$

Proof. Without loss of generality, assume that v_0 is the originator and that v_0 informs v_1 at time $k = 1$ and v_{n-1} at time $k = 2$. In models M_1 and M_2 , at time $k \geq 3$ the message is passed from from vertex v_{k-1} to v_k and from vertex v_{n-k+2} to v_{n-k+1} . Thus, at time $\lceil \frac{n}{2} \rceil$ all vertices on the path $v_0, v_1, \dots, v_{\lceil \frac{n}{2} \rceil}$ are informed as well as all vertices on the path $v_0, v_{n-1}, \dots, v_{\lceil \frac{n}{2} \rceil - 1}$. Hence, all vertices are informed and broadcasting is completed at time $\lceil \frac{n}{2} \rceil$.

The results for model M_3 can be derived similarly, taking into account that the average time to pass a message from v_k to v_{k+1} is 1.5 due to the potential time spent sending the message back to v_{k-1} . □

3. Hypercubes

Let Q_d denote the binary hypercube of dimension d . We define hypercubes as follows: The graph Q_d has 2^d vertices. These vertices are labeled with binary strings of length d . Two vertices are connected iff their labels differ by exactly one bit. For example, $(1000 \dots 01)$ and $(0000 \dots 01)$ are connected, but $(1010 \dots 01)$ and $(0000 \dots 01)$ are not. We will, in general, denote the label of a vertex u by $(u_1 u_2 \dots u_d)$, where $u_i \in \{0, 1\}$ for $i = 1, 2, \dots, d$, and the edge between vertices u and v by (u, v) .

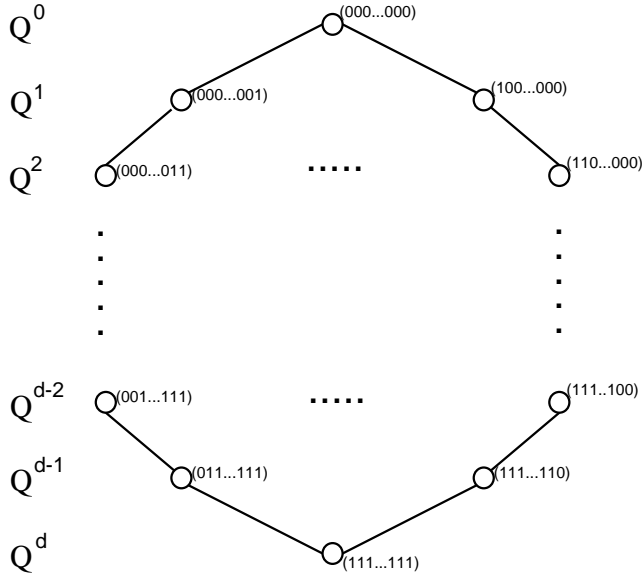


Fig. 4. The levels of the hypercube Q_d .

Hypercubes are interesting for a number of reasons. They are not only of theoretical interest, but are a popular topology for real-world interconnection networks. Hypercubes also have optimal performance under the classical broadcasting model; in fact, hypercubes are *minimum broadcast graphs* [3] and [6].

Under “messy” broadcasting, however, the worst case performance of hypercubes is $\Theta(d^2)$ for models M_2 and M_3 , and the worst case time for model M_1 is between $\Theta(d)$ and $\Theta(d^2)$ [9]. To our knowledge, finding the exact value of $t_1(Q_d)$ remains an open problem. In the following, we focus on tightly estimating $E[T_{3,Q_d}]$ and $E[T_{2,Q_d}]$; these average bounds are good benchmarks for the performance of hypercubes under “messy” broadcasting. Finding or approximating $E[T_{1,Q_d}]$ is future work.

We denote the $d + 1$ levels of Q_d by Q^0, Q^1, \dots, Q^d , where Q^i is the set of all vertices $u \in Q_d$ such that u 's label contains exactly i 1's (see Fig. 4). For example, $(1010 \dots 0) \in Q^2$ and $(1111 \dots 1) \in Q^d$. The number of binary strings in Q^i is $\binom{d}{i} = \frac{d!}{i!(d-i)!}$; in particular, $Q^0 = \{(000 \dots 0)\}$ and $Q^d = \{(111 \dots 1)\}$.

Before moving further we must establish the following identity.

Lemma 3.1. *If d and i are both integers and $d > i$ then*

$$\sum_{m=0}^{i-1} \frac{(d-i+m-1)!}{m!} = \frac{i(d-1)!}{(d-i)!}.$$

Proof. We proceed by induction on i . Clearly, when $i = 1$ we have

$$\sum_{m=0}^{i-1} \frac{(d-i+m-1)!}{m!} = \frac{(d-1+0-1)!}{0!} = (d-2)!$$

and

$$\frac{i(d-1)!}{(d-i)i!} = \frac{1(d-1)!}{(d-1)1!} = (d-2)!.$$

Hence, the identity holds for $i = 1$. Assuming the identity holds for i we must now show that it also holds for $i + 1$, i.e.,

$$\sum_{m=0}^{(i+1)-1} \frac{(d-(i+1)+m-1)!}{m!} = \frac{(i+1)(d-1)!}{(d-(i+1))(i+1)!}.$$

Substituting $d = x + 1$ into the left hand side and splitting off the $m = i$ term yields

$$\sum_{m=0}^{i-1} \frac{(x-i+m-1)!}{m!} + \frac{(x-1)!}{i!}.$$

Applying our inductive hypothesis to the sum, this simplifies to

$$\frac{i(x-1)!}{(x-i)i!} + \frac{(x-1)!}{i!}.$$

Substituting $x = d - 1$ back into the above leaves us with

$$\frac{i(x-1)!}{(x-i)i!} + \frac{(x-1)!}{i!} = \frac{i(d-2)!}{(d-i-1)i!} + \frac{(d-2)!}{i!}$$

which simplifies to

$$\frac{(d-2)!(d-1)}{(d-i-1)i!} = \frac{(i+1)(d-1)!}{(d-(i+1))(i+1)!}.$$

Hence, the identity holds for all $i \geq 1$ and the result is proved. □

In order to analyze broadcasting in the hypercube we must first introduce the idea of the initial path of a broadcast. If vertex $v_0 = (00\dots 0)$ originates the broadcast it will inform some vertex v_1 in level one at time 1. We define v_2 to be the first vertex in level two that is informed by v_1 . In general, we define v_i to be the first node in level i that is informed by v_{i-1} . The path continues until we reach we reach vertex $v_d = (11\dots 1)$. The sequence of vertices v_0, v_1, \dots, v_d is defined as the initial path. It is important to note that other paths the broadcast follows may propagate through the levels of the hypercube at different speeds than the initial path.

Lemma 3.2. *Let X_i be the random variable denoting the amount of time needed to pass a message from a vertex in level i to a vertex in level $i + 1$ for $i = 0, 1, 2, \dots, d - 1$ on the initial path. Then,*

$$E[X_i] = \frac{d+1}{d-i+1}.$$

Proof. Using the expected value formula, we first calculate $E[X_1]$, $E[X_2]$, and $E[X_3]$ as follows:

$$\begin{aligned} E[X_1] &= 1 * Pr\{X_1 = 1\} + 2 * Pr\{X_1 = 2\} \\ &= \frac{d-1}{d} + 2 * \left(\frac{1}{d} * \frac{d-1}{d-1}\right) \\ &= \frac{d+1}{d}, \end{aligned}$$

$$\begin{aligned} E[X_2] &= 1 * Pr\{X_2 = 1\} + 2 * Pr\{X_2 = 2\} + 3 * Pr\{X_2 = 3\} \\ &= \frac{d-2}{d} + 2 * \left(\frac{2}{d} * \frac{d-2}{d-1}\right) + 3 * \left(\frac{2}{d} * \frac{1}{d-1} * \frac{d-2}{d-2}\right) \\ &= \frac{d+1}{d-1}, \end{aligned}$$

$$\begin{aligned} E[X_3] &= 1 * Pr\{X_3 = 1\} + 2 * Pr\{X_3 = 2\} + 3 * Pr\{X_3 = 3\} + 4 * Pr\{X_3 = 4\} \\ &= \frac{d-3}{d} + 2 * \left(\frac{3}{d} * \frac{d-3}{d-1}\right) + 3 * \left(\frac{3}{d} * \frac{2}{d-1} * \frac{d-3}{d-2}\right) \\ &\quad + 4 * \left(\frac{3}{d} * \frac{2}{d-1} * \frac{1}{d-2} * \frac{d-3}{d-3}\right) \\ &= \frac{d+1}{d-2}. \end{aligned}$$

Continuing in this fashion we arrive at:

$$E[X_i] = \frac{d-i}{d} + \sum_{j=2}^{i+1} \left(j * \left(\prod_{k=0}^{j-2} \frac{i-k}{d-k} \right) * \frac{d-i}{d-j+1} \right).$$

Obviously,

$$\prod_{k=0}^{j-2} \frac{i-k}{d-k} = \frac{i!(d-j+1)!}{d!(i-j+1)!}.$$

Hence, we have

$$E[X_i] = \frac{d-i}{d} + \frac{i!(d-i)}{d!} \sum_{j=2}^{i+1} \frac{j(d-j)!}{(i-j+1)!}.$$

Next, we make the substitution $m = i - j + 1$

$$E[X_i] = \frac{d-i}{d} + \frac{i!(d-i)}{d!} \sum_{m=0}^{i-1} \frac{((i+1)-m)(d-(i+1-m))!}{m!}.$$

Clearly,

$$E[X_i] = \frac{d-i}{d} + \frac{i!(d-i)}{d!} \left((i+1) \sum_{m=0}^{i-1} \frac{(d-i+m-1)!}{m!} - \sum_{m=1}^{i-1} \frac{(d-i+m-1)!}{(m-1)!} \right).$$

Applying Lemma 3.1 to the left sum we can simplify the above to

$$E[X_i] = \frac{d-i}{d} + \frac{i!(d-i)}{d!} \left((i+1) \frac{i(d-1)!}{(d-i)!i!} - \sum_{m=1}^{i-1} \frac{(d-i+m-1)!}{(m-1)!} \right).$$

Next, we re-index the remaining sum so that it starts at $m = 0$ and make the substitution $d = x - 1$

$$E[X_i] = \frac{d-i}{d} + \frac{i!(d-i)}{d!} \left((i+1) \frac{i(d-1)!}{(d-i)!i!} - \sum_{m=0}^{i-2} \frac{(x-i+m-1)!}{m!} \right).$$

Using the fact that

$$\sum_{m=0}^{i-2} \frac{(x-i+m-1)!}{m!} = \sum_{m=0}^{i-1} \frac{(x-i+m-1)!}{m!} - \frac{(x-2)!}{(i-1)!}$$

we can apply Lemma 3.1 to the above to get

$$E[X_i] = \frac{d-i}{d} + \frac{i!(d-i)}{d!} \left((i+1) \frac{i(d-1)!}{(d-i)!i!} - \frac{(x-1)!i}{(x-i)!i!} + \frac{(x-2)!}{(i-1)!} \right).$$

Substituting $x = d + 1$ back into the equation yields

$$E[X_i] = \frac{d-i}{d} + \frac{i!(d-i)}{d!} \left((i+1) \frac{i(d-1)!}{(d-i)!i!} - \frac{d!i}{(d-i+1)!i!} + \frac{(d-1)!}{(i-1)!} \right)$$

which can be simplified to

$$E[X_i] = \frac{d+1}{d-i+1}.$$

This completes the proof. □

Theorem 3.1. $E[T_{3,Q_d}] \leq (d+1) \sum_{j=1}^d \frac{1}{j} = \Theta(d \log d).$

Proof. Using the symmetry of hypercubes, we assume, without loss of generality, that $v_0 = (00\dots 0)$ is the originator. We first show that the average number of time units necessary for $(11\dots 1)$ to be informed is less than or equal to $1 + (d+1) \sum_{j=2}^d \frac{1}{j}$. One thing we should point out, is that broadcasting does not complete in general even if the furthest vertex $(11\dots 1)$ from the originator has been informed.

Let X be the random variable denoting the total amount of time spent to inform vertex $(11\dots 1)$ from the originator on the initial path. Then $X = X_0 + X_1 + \dots + X_{d-1}$ and the expected value of X is

$$\begin{aligned} E[X] &= E[X_0] + E[X_1] + E[X_2] + \dots + E[X_{d-1}] \\ &= 1 + \frac{d+1}{d} + \frac{d+1}{d-1} + \dots + \frac{d+1}{2} \\ &= 1 + (d+1) \sum_{j=2}^d \frac{1}{j}. \end{aligned}$$

Since we are tracing only one of many paths from the originator to vertex $(11 \dots 1)$, we must take into account that on average some of the other paths will be faster than our initial route. Therefore, the average number of time units to inform vertex $(11 \dots 1)$ is less than or equal to $1 + (d + 1) \sum_{j=2}^d \frac{1}{j}$, which is only the average speed of the initial route.

Because broadcasting is not necessarily completed by time $1 + (d + 1) \sum_{j=2}^d \frac{1}{j}$ when vertex $(11 \dots 1)$ is informed by our initial path, we allow an additional d time units to pass so that every vertex in Q_d can complete broadcasting to its neighbors in the levels above and below it. Each vertex in Q_d is connected to d other vertices, so these d additional time units ensure that each informed vertex can broadcast to each of its d neighbors. Since we have already formed an initial path, one or more vertices (all, or nearly all in the upper levels) are informed in each level, so vertices in all levels are broadcasting simultaneously to their d neighbors during these d time units ensuring that broadcasting does indeed complete. Therefore, the average-speed of this route is an upper bound for the average-case broadcasting time. This completes the proof of Theorem. 3.1 \square

We must admit that the above result is only an upper bound of average-case broadcasting time and our simulation of M_3 supports an even stronger conclusion of $\Theta(d)$, rather than $\Theta(d \log d)$. Unfortunately, we are unable to provide an actual proof at this moment.

Theorem 3.2. $E[T_{2,Q_d}] \leq d \sum_{j=1}^d \frac{1}{j} = \Theta(d \log d)$.

Proof. Mimicking the proof of Theorem 3.1, we note that under model M_2 , no vertex ever informs the vertex (or vertices) that informed it. Thus, the average amount of time needed to pass a message from a vertex on level i to a vertex on level $i + 1$ is $\frac{d}{d-i+1}$. Hence, the average-case time to form an initial path from the originator to vertex $(11 \dots 1)$ is less than or equal to $1 + d \sum_{j=2}^d \frac{1}{j} = \Theta(d \log d)$. We allow $d - 1$ additional time units to pass, rather than d , accounting for the fact that no vertex will ever call back to the one that informed it. This extra time ensures that the broadcast completes after the initial path is formed. \square

Unfortunately, it seems impossible to deal with M_1 in the same manner due to difficulties of computing expected values of $E[X_i]$ on any initial path, because some vertices have been informed at level of $i - 1$ with unknown probabilities.

Feige, Peleg, Raghavan and Upfal [4] found high-probability bounds for broadcasting in a hypercube under a slightly different model: At each step, every vertex that knows of the message chooses one of its neighbors in Q_d uniformly at random, and informs it of the message. Let H_d be the number of time units required for broadcasting to complete. Then $H_d = \Theta(d)$ is true with probability $1 - 1/2^d$.

4. Complete d -ary Trees

According to [9], a full d -ary tree can be defined recursively as follows: A full d -ary tree is either a single vertex (the root), or it consists of a distinguished vertex (the root) with d

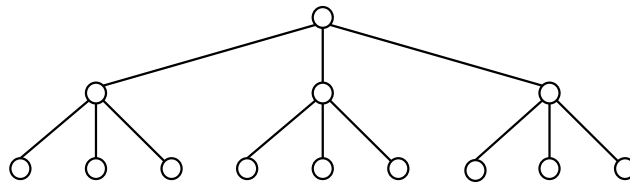


Fig. 5. $T_{3,3}$.

children, each of which is the root of a full d -ary tree. A complete d -ary tree is a full d -ary tree such that every leaf is at the same distance $(h-1)$ from the root (the height of such a d -ary tree is h). We use $T_{d,h}$ to denote the complete d -ary tree of height h and define the depth of a node to be its distance from the root. The ternary tree $T_{3,3}$ is shown in Fig. 5.

Theorem 4.1. *Let u be the originator in the complete d -ary tree $T_{d,h}$. Then*

$$E[T_{3,u,T_{d,h}}] = \begin{cases} d + \frac{d^2+2d}{d+1}(h-2) & \text{if } u \text{ is the root,} \\ 1 + d - \frac{1}{d} + \frac{(d+2)(3d+1)}{2(d+1)}(h-2) & \text{if } u \text{ is a leaf,} \\ \frac{d+2}{2}i + d - \frac{1}{d} + \frac{d^2+2d}{d+1}(h-2) & \text{if } u \text{ is at } i\text{th depth} \\ & \text{for } i = 1, 2, \dots, h-2. \end{cases}$$

Proof. Let us first consider case 1: the originator u is the root. It then takes d time units for u to inform its d children. Without loss of generality, we assume that the right-most child, which we will call v , is the last to be informed. Under model M_3 , at each time unit every vertex must transmit the message to one of its neighbors to which it has not yet sent the message. Thus, each vertex that is not the root or the last leaf to be informed must send the message once along each of its $d+1$ (or 1, if the node is a leaf, and not the last leaf to be informed) edges. Hence, v takes $d+1$ time units to broadcast to its $d+1$ neighbors, and, on average, $d+1 - \frac{1}{d+1}$ time units to inform its d children due to the contribution of u .

The same argument applies to subsequent vertices, down to and including the vertices whose children are leaves. We therefore get that the average time is

$$d + (d+1 - \frac{1}{d+1})(h-2) = d + \frac{d^2+2d}{d+1}(h-2).$$

Now we assume the originator is a leaf (case 2) which has distance $h-1$ from the root. Obviously it takes one time unit to inform its parent and $\frac{d+2}{2} (\frac{1}{d+1} + \frac{2}{d+1} + \dots + \frac{d+1}{d+1} = \frac{d+2}{2})$ time units to go to each higher level up to the root. Thus, it needs $1 + \frac{d+2}{2}(h-2)$ to reach the root from the leaf. Since one child of the root has been informed, it only takes $d - \frac{1}{d}$ time units on average for the root to pass a message to its all d children. The rest follows from case 1. We sum the total broadcasting time as

$$1 + \frac{d+2}{2}(h-2) + d - \frac{1}{d} + \frac{d^2+2d}{d+1}(h-2)$$

which proves case 2.

Case 3, in which the originator is neither the root nor a leaf, follows easily. \square

We can similarly derive the following:

Theorem 4.2. *Let u be the originator in the complete d -ary tree $T_{d,h}$. Then*

$$E[T_{1,u,T_{d,h}}] = E[T_{2,u,T_{d,h}}] = \begin{cases} d(h-1) & \text{if } u \text{ is the root,} \\ d + \frac{3d+1}{2}(h-2) & \text{if } u \text{ is a leaf,} \\ \frac{d+1}{2}(i-1) + d(h-\frac{1}{2}) & \text{if } u \text{ is at } i\text{th depth} \\ & \text{for } i = 1, 2, \dots, h-2. \end{cases}$$

Proof. If u is the root, it takes d time units for the message to fully propagate to the next level of the tree. Multiplying this by the $h-1$ levels the message must pass through yields $d(h-1)$ time units for broadcasting to complete.

If u is a leaf, one time unit is spent broadcasting to level $h-2$, and $\frac{d+1}{2}(h-2)$ time units are spent on average propagating the message up to the root. Once the message reaches the root it takes $d-1$ time units to propagate to each child of the root, and $d(h-2)$ time units for the message to travel back down the tree. Summing each of these times yields our result.

Finally, if u is neither the root nor a leaf, at the beginning it takes $\frac{d+2}{2}$ time units on average for the message to move up one level, as no adjacent nodes are informed, and $\frac{d+1}{2}$ time units to move up subsequent levels, as exactly one adjacent node is informed. Thus, the time to inform the root is $\frac{d+2}{2} + \frac{d+1}{2}(i-1)$. The rest follows from our previous analysis. \square

5. Complete Graphs under Model M_1

We now turn our attention to the average-case analysis of model M_1 on K_n , the complete graph on n vertices. For convenience, let these vertices be enumerated v_0, v_1, \dots, v_{n-1} .

We assume at time k that r vertices are informed and $n-r$ are uninformed. Each informed vertex randomly informs one of $n-r$ uninformed vertices at time $k+1$ with probability $\frac{1}{n-r}$; hence, each arrangement occurs with probability $\frac{1}{(n-r)^r}$. We seek the probability $P_m(r, n-r)$ of finding exactly m vertices uninformed at time $k+1$.

Let A_i be the event that vertex v_i is uninformed, for $i = 1, 2, \dots, n-r$. In this event, the r informed vertices could inform all the remaining $n-r-1$ vertices, and this could be done in $(n-r-1)^r$ different ways. Similarly, there are $(n-r-2)^r$ arrangements, leaving two preassigned vertices uninformed, etc. Accordingly,

$$P_i = Pr\{A_i\} = \frac{(n-r-1)^r}{(n-r)^r} = \left(1 - \frac{1}{n-r}\right)^r, \text{ where } 1 \leq i \leq n-r,$$

$$P_{ij} = Pr\{A_i A_j\} = \left(1 - \frac{2}{n-r}\right)^r, \text{ where } 1 \leq i < j \leq n-r,$$

$$P_{ijk} = Pr\{A_i A_j A_k\} = \left(1 - \frac{3}{n-r}\right)^r, \text{ where } 1 \leq i < j < k \leq n-r, \text{ etc.}$$

Let $S_1 = \sum P_i, S_2 = \sum P_{ij}, S_3 = \sum P_{ijk}$, etc. Note that in these sums each combination appears once and only once. Hence, for every $\nu \leq n - r$,

$$S_\nu = \binom{n-r}{\nu} \left(1 - \frac{\nu}{n-r}\right)^r.$$

The probability that at least one vertex is uninformed is given by

$$P = S_1 - S_2 + S_3 - S_4 + \dots \pm S_{n-r},$$

(see [5]) and hence, we find that the probability that all vertices are informed is

$$\begin{aligned} P_0(r, n-r) &= 1 - P \\ &= 1 - (S_1 - S_2 + S_3 - S_4 + \dots \pm S_{n-r}) \\ &= \sum_{\nu=0}^{n-r} (-1)^\nu \binom{n-r}{\nu} \left(1 - \frac{\nu}{n-r}\right)^r. \end{aligned}$$

Consider now a distribution in which exactly m vertices are uninformed. These m vertices can be chosen in $\binom{n-r}{m}$ ways. The r informed vertices broadcast to the remaining $n - r - m$ vertices so that each of these vertices is informed. The number of such distributions is

$$(n - r - m)^r P_0(r, n - r - m).$$

Dividing by $(n - r)^r$, we find that the probability that exactly m vertices remain uninformed is

$$\begin{aligned} P_m(r, n-r) &= \binom{n-r}{m} \left(1 - \frac{m}{n-r}\right)^r P_0(r, n - r - m) \\ &= \binom{n-r}{m} \sum_{\nu=0}^{n-r-m} (-1)^\nu \binom{n-r-m}{\nu} \left(1 - \frac{m+\nu}{n-r}\right)^r \end{aligned}$$

by using

$$\left(1 - \frac{m}{n-r}\right)^r \left(1 - \frac{\nu}{n-r-m}\right)^r = \left(1 - \frac{m+\nu}{n-r}\right)^r.$$

Finally, we are ready to prove the following:

Theorem 5.1. *Let V_k be the number of vertices informed by time k . Then,*

$$E[T_1, K_n] = \min \{k \mid \lceil E[V_k] \rceil = n\}$$

where

$$E[V_k] = n - \sum_{m=1}^{n - \lceil E[V_{k-1}] \rceil} m P_m(\lceil E[V_{k-1}] \rceil, n - \lceil E[V_{k-1}] \rceil)$$

for $k > 1$, with initial condition $E[V_1] = 2$.

Proof. Clearly, we have

$$\begin{aligned} E[V_k] &= E[V_{k-1}] + \text{average number of new vertices informed at time } k \\ &= E[V_{k-1}] + (n - E[V_{k-1}]) - \text{average vertices uninformed at time } k \\ &= n - \sum_{m=1}^{n - \lceil E[V_{k-1}] \rceil} m P_m(\lceil E[V_{k-1}] \rceil, n - \lceil E[V_{k-1}] \rceil). \end{aligned}$$

This completes the proof of theorem. \square

We have encountered difficulties while solving the above recurrence mathematically. However, we both stimulated model M_1 directly using the following algorithm for n up to 2^{29} with 1000 trials, and computed the recursion in Theorem 5.1 using Maple 8. The two results coincide and are very approximately equal to $\lceil \log n \rceil + 2$ for $n \geq 2^{10}$, and are between $\lceil \log n \rceil$ and $\lceil \log n \rceil + 2$ for $n < 2^{10}$, which indicates that the performance of M_1 on complete graphs is close to that of classical broadcasting.

```

Algorithm M1Simulation( $n$ )
   $k \leftarrow 0$  // time units
   $i \leftarrow 1$  // informed nodes
   $u \leftarrow n - 1$  // uninformed nodes
  START:
   $j \leftarrow 0$  // newly informed nodes at time  $k$ 
   $k \leftarrow k + 1$ 
  for  $x \leftarrow 1$  to  $i$  do
     $z \leftarrow \text{random}(u)$  //  $z$  gets a random number in  $[1, u]$ 
    if  $z > j$  then // if no collision
       $j \leftarrow j + 1$  // inform a new node
    if  $j = u$  then // if all informed this cycle
      goto end
   $i \leftarrow i + j$  // increase informed nodes
   $u \leftarrow u - j$  // decrease uninformed nodes
  goto start
  END:
  print  $k +$  " time units required"

```

Table 1 summarizes the results of this algorithm averaged over 1000 trials, which matches with data computed directly from the recurrence in Theorem 5.1 and clearly shows that the average-case time of $\lceil \log n \rceil + 2$ is much faster than the worst-case time of $n - 1$. The column *Time* represents the number of time units needed to complete broadcasting while the column *Time*($\log(n) + k$) shows the time needed to finish broadcasting split into two terms, the first being $\log(n)$ and the second being the additional time needed beyond the $\log(n)$ time units.

We know from [9] that $t_i(K_n) = n - 1$ for all i . Here, we have another opportunity to show that worst-case messy broadcast times are often highly improbable.

Corollary 5.1. $Pr\{T_{1,v_0,K_n} = n - 1\} = \prod_{i=2}^{n-1} \frac{1}{(n-i)^{i-1}}$.

Proof. Assume, without loss of generality, that vertex v_0 broadcasts to v_i at time i for all i until broadcasting is complete.

There is a $\frac{1}{n-2}$ chance that v_0 and v_1 both broadcast to v_2 at time 2. Given that this occurs, there is a $\frac{1}{(n-3)^2}$ chance that vertices v_0 , v_1 , and v_2 all broadcast to v_3 at time 3. In general, there is a $\frac{1}{(n-i)^{i-1}}$ chance that vertices v_0 through v_{i-1} broadcast to v_i at time i ,

Table 1. Simulation Results for Model M_1 .

# of Nodes (n)	$\log(n)$	Time	Time ($\log(n) + k$)
2^1	1	1.000	$1 + 0.000$
2^2	2	2.499	$2 + 0.499$
2^3	3	3.990	$3 + 0.990$
2^4	4	5.149	$4 + 1.149$
.....			
2^8	8	9.941	$8 + 1.941$
2^9	9	10.998	$9 + 1.998$
2^{10}	10	12	$10 + 2.000$
2^{11}	11	13	$11 + 2.000$
2^{12}	12	14	$12 + 2.000$
2^{13}	13	15	$13 + 2.000$
.....			
2^{26}	26	28	$26 + 2.000$
2^{27}	27	29	$27 + 2.000$
2^{28}	28	30	$28 + 2.000$
2^{29}	29	31	$29 + 2.000$

given that for all $k < i$, all informed vertices broadcasted to v_k at time k . The result follows from the product of these conditional probabilities. □

For large n , the probability shown in Corollary 5.1 is effectively zero.

Finally, we would like to mention that the following variant of broadcasting has been given by Frieze and Grimmett [7]. A complete graph contains n vertices with one originator. At each time unit, each informed vertex informs another vertex randomly chosen from the graph independently of other choices (hence repetition is possible during broadcasting, which is different from M_1). Let S_n be the number of time units required for broadcasting to complete. Then

$$\frac{S_n}{\log n} \rightarrow 1 + \log_e 2$$

in probability as $n \rightarrow \infty$. Furthermore, Pittel [12] improved this result, showing that

$$S_n = \log n + \log_e n + o(1).$$

Given that this model of “messy” broadcasting makes less assumptions about the informed status of neighbours than models M_1 , M_2 , and M_3 , it is reasonable to expect that models M_1 , M_2 , and M_3 perform more efficiently than the model considered in [7].

Acknowledgments

We would like to thank Dr. Michael J. Wichura of the University of Chicago for his prompt advice concerning the occupancy problem which helped us in the analysis of complete graphs

under model M_1 , and also Marc Berndl, University of Toronto, for his help in refining Theorem 3.1.

The Natural Sciences and Research Council of Canada (NSERC) provided three of the authors with research grants. Chenkuan Li was supported by an NSERC Research Grant, and Tom Hart and Kevin Henry were supported by NSERC Undergraduate Student Research Awards.

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